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Extracting Explanation from Artificial Neural Networks

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Abstract: - Artificial neural networks (ANN) are very efficient in solving various kinds of problems. But Lack of explanation capability (Black box nature of Neural Networks) is one of the most important reasons why artificial neural networks do not get necessary interest in some parts of industry. In this work artificial neural networks first trained and then combined with decision trees in order to fetch knowledge learnt in the training process. After successful training, knowledge is extracted from these trained neural networks using decision trees in the forms of IF THEN Rules which we can easily understand as compare to direct neural network outputs. We use decision trees to train on the results set of trained neural network and compare the performance of neural networks, and decision trees in knowledge extraction from neural networks. Weka machine learning simulator with version 3.7.5 is used for research purpose. The experimental study is done on bank customers' data which have 12 attributes and 600 instances. The results study show that although neural networks takes much time in training and testing but are more accurate in classification then decision trees.

Keywords--: Symbolic Interpretation of Neural Networks, **Rules Extraction, Decision Trees, If Then Rules**

I. INTRODUCTION

Knowledge Analysis. It is a popular suite of machine Artificial Neural Networks (ANNs) are used in many learning software written in Java, developed at the applications to solve various kinds of problems. However the University of Waikato. WEKA is free software available major problem with Neural Networks is that decision given by under the GNU General Public License [6]. MATLAB is Neural Networks is Difficult to understand by human being another tool used for completing our research work. This is because the knowledge in the Neural Networks is stored

TREES

as real valued parameters (weights and biases) of the networks [1]. Their biggest weakness is that the knowledge they acquire is represented in a form not understandable to humans. Researchers tried to address this problem by extracting rules from trained Neural Networks. Even for an ANN with only single hidden layer, it is generally impossible to explain why a particular pattern is classified as a member of one class and another pattern as a member of another class, due to the complexity of the Network [2]. Decision trees can be easily represented in the form of IF THEN RULES and hence extracting decision trees are probably one of the best methods of interpreting a neural network [16]. Pruning of the tree is used to prevent over-fitting of the data. This pruning mechanism maximizes information gain by getting rid of nodes that do not contribute much to information gain.

RULES EXTRACTION METHODS

A) Decompositional Approach: This approach is also called local method. Decompositional or local methods extract rules from level of individual, hidden and output, units within the trained neural network. The rules extracted from these small networks are combined to form a global relationship. The earliest decompositional rule extraction method is the KT algorithm developed by Fu [3].

B) Pedagogical Approach: This approach treats the network as a 'black box' and make no attempt to disassemble its architecture to examine how it works;

instead this approach extracts rules by examining the relationship between the inputs and outputs [4]. The pedagogical approach is faster then decompositional approach. One problem with this method is that the size of the search space can grow exponentially with the number of input values. The rule-extraction-as-learning technique of Craven and Shavlik (1994) is example of this technique.

C. Eclectic Approach: Eclectic approach combines the previous approaches, analyse the ANN at the individual unit level but also extract rules at the global level. One example of this approach is the method proposed by Tickle et al. (called DEDEC.) DEDEC extracts if then rules from MLP networks trained with back propagation algorithm [5],[13]

III. DATA AND TOOL USED:

DATA: In this work the data we used is purely real time data. It is combination of primary and secondary data. Data is based upon bank customer account. Data is divided into training set and testing set. We used different proposition of training and testing data to produce better results.

TOOL: The tool we used in this research work WEKA. WEKA is abbreviation of Waikato Environment for

IV. RESEARCH METHODOLOGY NEURAL NETWORK Can be explained better using NFURAL DECISION TREE MODEL NETWORK MODEL **IF-THEN** Implies Rules EXTRACT DECISION TREES FROM TRAINED NEURAL DECISION Can be easily expressed as NETWORK MODELS

Figure 1. Extracting decision trees from neural networks

As in figure 1 above it can be seen that both decision trees and neural networks can be easily converted into IF THEN Rules or we can simply convert neural networks into decision trees. We can use any neural networks architecture like feed forward network, radial basis Function networks, support vector machine, recurrent networks etc[7].

Combining neural networks with decision trees:

The goal of knowledge extraction from ANN's is to find the knowledge stored in the networks weights in symbolic form. One main concern is the fidelity of the extraction process, i.e. how accurately the extracted knowledge corresponds to knowledge stored in networks. There are two main approaches for knowledge extraction from trained neural networks.

A. Extraction of if then rules by clustering the activation values of hidden state neurons.

B. The application of machine learning methods such as decision trees on the observation of input outputs mappings of trained networks when presented with data.

V: TRAINING AND TESTING OF FEED FORWARD NEURAL Network

Multilayer Perceptron:

A multilayer perceptron in weka is a feed forward artificial neural network model that maps sets of input data onto a set of appropriate output. It is a modification of the standard linear perceptron in that it uses three or more layers of neurons (nodes) with nonlinear activation functions, and is more powerful than the perceptron in that it can distinguish data that is not linearly separable, or separable by a hyper-plane [8]. The error signals are used to calculate the weight updates which represent knowledge learnt in the networks. The performance of Backpropogation algorithm can be improved by adding a momentum term [9], [10]. The error in back propagation algorithm is minimised by using formula.

$$E = \frac{1}{2} \sum_{i=1}^{n} (t_i - y_i)^2$$

Where n=number of epochs, ti is desired target value associated with ith epoch and yi is output of the network .To train the network with minimum possibility of error we adjust the weights of the network[11].

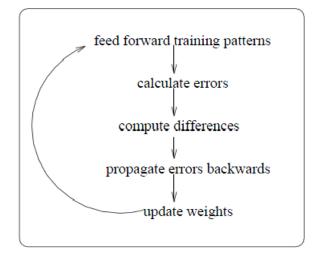


Figure 2: The back-propagation Neural network Epoch [12]

Table1: Defining the Network Parameters

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Parameter	Values		
Number of Training Data	600		
Number of Testing Data	100		
Number of Hidden Layers	2		
Learning Rate	0.3		
Momentum	0.2		
Validation Threshold	20		
Total no of Epochs	250		
Error Per Epoch	0.019		
Accuracy	98.6577 %		

The above table shows maximum accuracy obtained during training of multilayer perceptron with 10 cross validation. For the cross validation purpose we divide 70% data for training, 15% data for validation and 15% data for testing of networks.

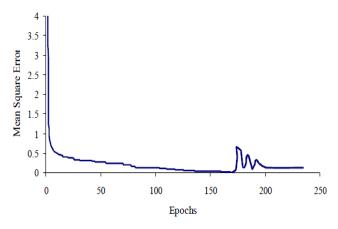


Figure 3: Errors vs. Epochs in 10 folds Cross Validation

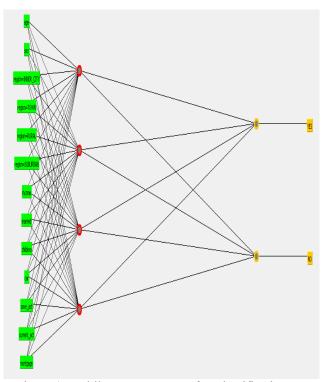


Figure 4: Multilayer Perceptron after classification

VI: EXTRACTION OF KNOWLEDGE FROM NEURAL NETWORKS IN THE FORM OF DECISION TREES

Decision Tree: Decision trees are machine learning tool for building a tree structure from a training dataset. A Decision tree learns by starting at the root node and select the best attributes which splits the training data[13]. Compared to neural networks they can explain how they arrive to a particular solution [14,15]. We will use decision trees to extract rules from the trained neural networks. We extracted decision trees from trained neural networks using j48 algorithm. We used the attribute and classification of the 75% training data and the attributes of the remaining 30% test data. A typical decision tree extracted from experiment No. 7 in table 2 as shown in figure 3. We show this particular decision tree because experiment No.7 has the best generalization performance from all experiment in table 2.

 Table 2: Decision Trees for classification on the results set (

 Network

			Time taken	Number
Exp	Training	Generalization	to build	of leaves
No	Performance	Performance	model in	and size
			sec	of tree
1	90.604%	86.576%	0.2	(7,13)
2	90.70%	86.5%	0.2	(8,15)
3	92.68%	86.5%	0.3	(8,15)
4	92.6%	86.7%	0.3	(9,15)
5	93.4%	86.5%	0.2	(9,15)
6	94.4%	86.8%	0.4	(7,12)
7	95.6%	90.60%	0.2	(7,10)
8	95.6%	88.3%	0.3	(7,9)
9	94.5%	87.6%	0.3	(5,6)
10	95.6%	89.5%	0.4	(6,7)

Time taken to build model: 0.02 seconds

=== Evaluation on training set === === Summary ===

Correctly Classified Instances	135	90.604 %
Incorrectly Classified Instances	14	9.396 %
Kappa statistic	0.8039	
Mean absolute error	0.1603	
Root mean squared error	0.2831	
Relative absolute error	32.9712 %	
Root relative squared error	57.4314 %	
Coverage of cases (0.95 level)	100 %	
Mean rel. region size (0.95 level)	86.2416 %	
Total Number of Instances	149	

=== Detailed Accuracy By Class ===

	TP Rate	FP Rate	Precision	Recall	F-Measure	ROC Area	Class
	0.839	0.046	0.929	0.839	0.881	0.93	YES
	0.954	0.161	0.892	0.954	0.922	0.93	NO
eighted Avg.	0.906	0.113	0.907	0.906	0.905	0.93	

=== Confusion Matrix ===

```
a b <-- classified as
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52 10 | a = YES
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4 83 | b = NO
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Fig 5: Best Performance of decision tree in exp no 7 of table 2 using weka

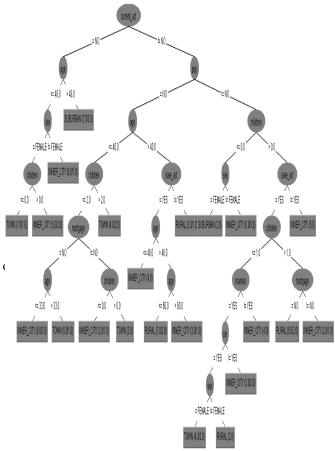


Fig 6: The figure show the decision tree extracted from trained neural network in experiment no 7 of table 2.

THE FOLLOWING RULE SET IS OBTAINED FROM THE DECISION TREE OF FIG 6:

I. Applying Remove redundancy conditions

In this step, we will remove the more general conditions which appear in the same rule with more specific conditions. For example

IF Children ≥ 1 AND Children >2AND Children >3 THEN Marital status =YES

We can see that the condition Children ≥ 1 is more specific than Children >3 and Children > 2. So we remove all such conditions. The final rule will be

IF Children ≥ 1 then Marital status = YES

Applying similar approach the following set of rules are extracted from fig 5 decision trees

Rule 1:

a) IF Current_act = NO AND Age ≤ 48.0 AND Sex = FEMALE AND Children ≤ 0 THEN Region = Town
b) IF AGE > 48.0 AND Region Suburban AND

 $Current_act = NO \text{ then } Pep = NO$

c) IF Children ≤ AND Mortgage = NO AND Age ≤THEN Region INNER_CITY

d) IF Age ≤AND Region TOWN AND Mortgage! = NO THEN Children =NO <u>II</u>. *For every pair decision trees Remove redundancy rules.* For example

- <u>Rule 1</u>: IF Age ≤ AND Salary ≤ 3500 AND Pep = NO THEN Mortage = YES
- <u>Rule 2</u>: IF Age ≤ 50 AND Salary ≤ 3500 AND Pep = NO THEN Mortage = YES
- <u>New Rule:</u> IF Age ≤ 50 AND Salary ≤ 3500 AND Pep = NO THEN Mortage =YES
- <u>Rule 3</u>: IF Children > 2 AND Region TOWN AND Age > 40 THEN Save act = YES

III. Remove more specific rules. The rules with a condition set which is a superset of another rule should be removed.

For example

- **<u>Rule 1:</u>** IF Age ≤ 60 AND Region = Rural AND Saving_ act = YES THEN Pep = NO
- **<u>Rule 2:</u>** IF Age <= 60 AND Children <= 1 AND Region =Rural AND Saving act = YES THEN Pep= NO
- <u>Rule 3:</u> IF Region = Rural AND Saving _ act =YES THEN Pep = NO
- <u>New Rule:</u> IF Region = Rural AND saving _ act =YES THEN Pep = NO
- **<u>Rule 4:</u>** Children = 0 and Sex = FEMALE AND Region = SUBURBAN AND INNER_CITY THEN Save act = YES

<u>IV.</u> Divide range of conditions. The rules of different branches with the same attribute which has overlapped range should be divided into several parts. For example:

- **<u>Rule 1:</u>** IF Marital status =Married AND Salary > 20000 THEN Children= YES
- <u>**Rule 2:</u>** IF Marital status=Married AND Salary < 35000 THEN Children = YES</u>
- <u>New Rule 1:</u> IF Marital status = Married AND Salary ≤ 35000 THEN Children= YES
- <u>New Rule 2:</u> IF Marital status= Married AND Salary ≤ 20000 THEN Children = YES

Table 3: Per	formance of	decision	trees vs.	neura	l networks	S
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Classification Approach	Training Performance	Generalization Performance	Training Time (Epochs)
ANN	93.5%	90.6%	170
Knowledge extract from trained ANN		88.9%	
Decision Tree	91.3%	89.2%	130

CONCLUSION AND FUTURE WORKS:

Neural networks have been successful in the classification of data we have. The prediction accuracy of neural networks can be increased by having more training instances in the dataset. Decision trees have been useful in knowledge extraction from trained neural networks. We have obtained rules for classification of bank customers according to their attributes values. The results show that however neural networks are good in generalization performance of given data set. However they cannot explain how they arrive to a solution. The extracted rules show that three major attributes age, region and mortage has major influence on the data set. The extraction of knowledge from these networks helps us to obtain useful rules which further helps in understanding the results obtain from neural networks. In the future works we can apply soft computing techniques to extract more easily to understand rules.

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